

$$L = \frac{v_0^2}{g} \sin(2\alpha)$$

$$\vec{R} = \vec{v}_0 t + \frac{1}{2} \vec{g} t^2 \quad (*) \quad \vec{g} = \begin{pmatrix} g \sin \alpha \\ 0 \\ -g \cos \alpha \end{pmatrix}$$

$$\begin{cases} g_x = g \sin \alpha \\ g_y = 0 \\ g_z = -g \cos \alpha \end{cases}$$

$$R_z = v_0 \sin \beta \cdot t + \frac{1}{2} (-g \cos \alpha) t^2$$

$$0 = v_0 \sin \beta \cdot T - \frac{1}{2} g \cos \alpha T^2$$

$$v_0 \sin \beta T = \frac{1}{2} g \cos \alpha T^2 \Rightarrow \begin{cases} 0 \\ T = \frac{2v_0 \sin \beta}{g \cos \alpha} \end{cases}$$

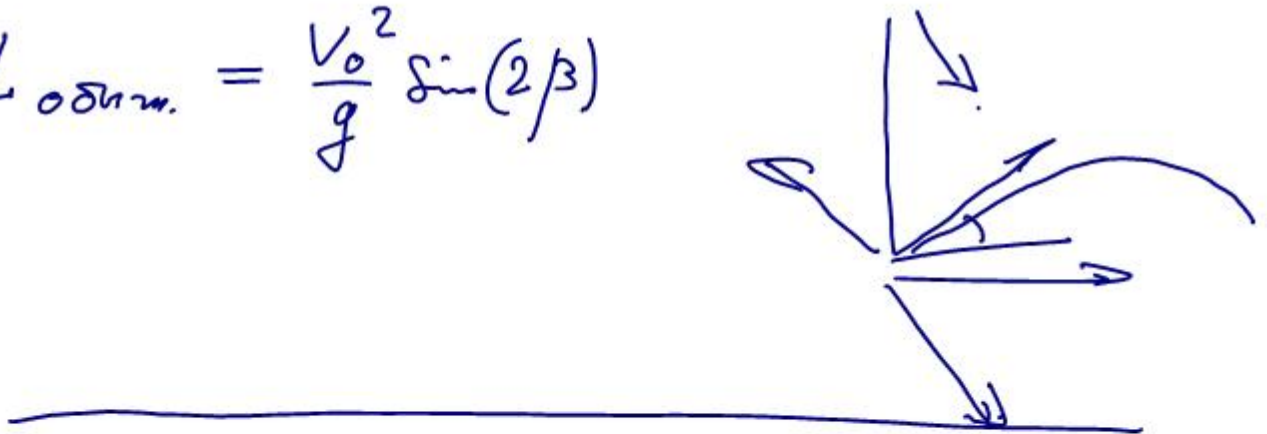
($T_{\text{obser.}} = \frac{2v_0 \sin \beta}{g}$)

$$R_x = v_0 \cos \beta \cdot t + \frac{1}{2} g \sin \alpha \cdot t^2 \quad L = v_0 \cos \beta \cdot \frac{2v_0 \sin \beta}{g \cos \alpha}$$

$$L = R_{\downarrow}(t=T) = v_0 \sin \beta \left(\frac{2v_0 \sin \beta}{g \cos \alpha} + \frac{1}{2} g \sin \alpha \frac{4v_0^2 \sin^2 \beta}{g^2 \cos^2 \alpha} \right)$$

$$= \frac{v_0^2}{g} \left(\frac{\sin(2\beta)}{\cos \alpha} + \frac{1}{2} \frac{\sin \alpha \sin^2 \beta}{\cos^2 \alpha} \right)$$

$$L_{\text{однм.}} = \frac{v_0^2}{g} \sin(2\beta)$$



Законы Ньютона (3-я классическая динамика).

$$\vec{R} \leftarrow \begin{cases} \vec{v}(t) \\ \vec{r}_0 \end{cases} \leftarrow \begin{cases} \vec{a}(t) \\ \vec{v}_0 \end{cases} \leftarrow \begin{cases} \vec{S}(t) \\ \vec{a}_0 \end{cases}$$

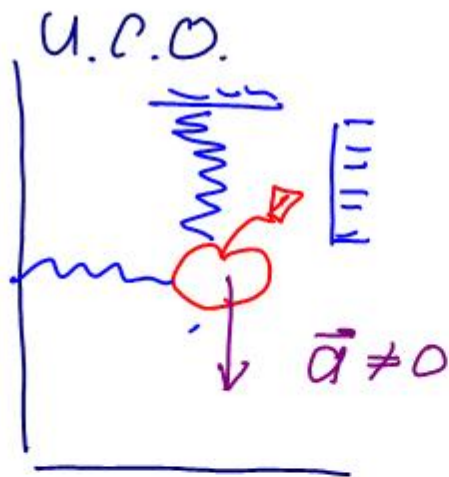
$$\vec{a} = \frac{\vec{F}}{m}$$



$$\vec{F} = m \vec{a}$$

$$\equiv \equiv$$

$$N_p \cdot m_p + N_n m_n + N_e \cdot m_e + \dots \equiv m$$



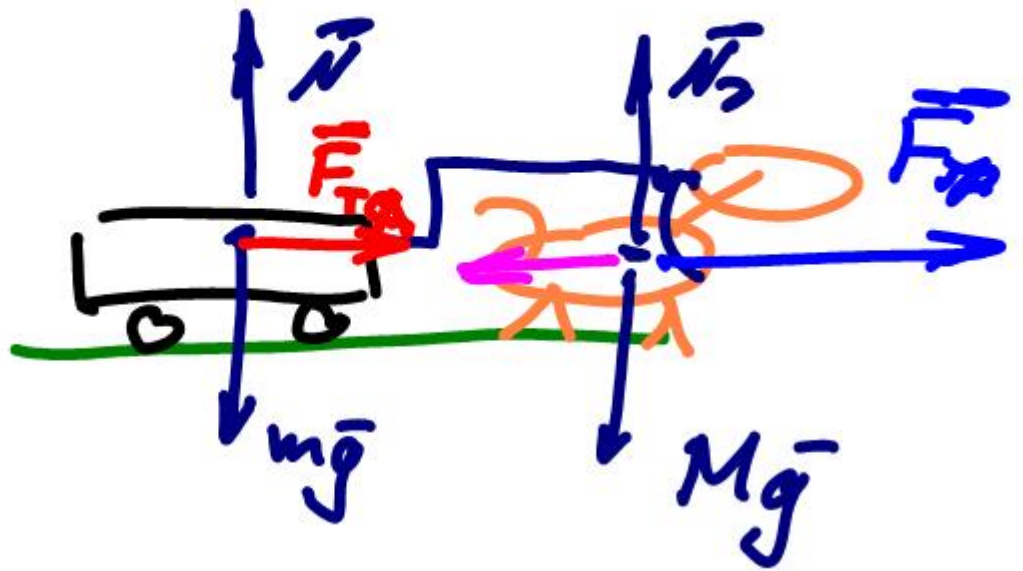
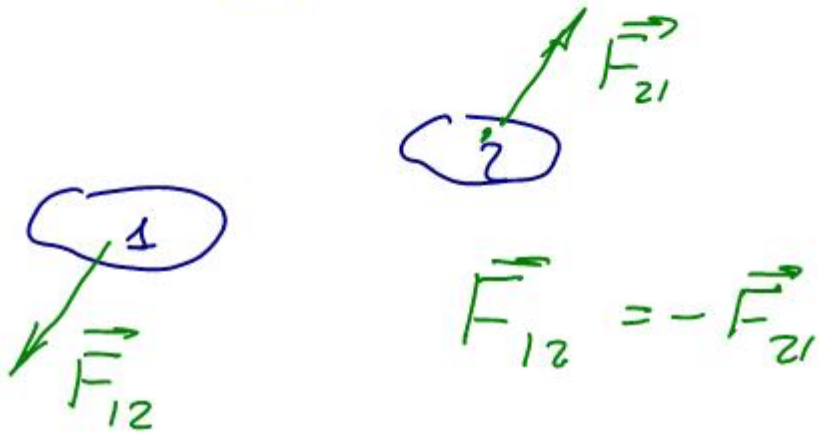
$$\vec{a} \sim \vec{F}$$

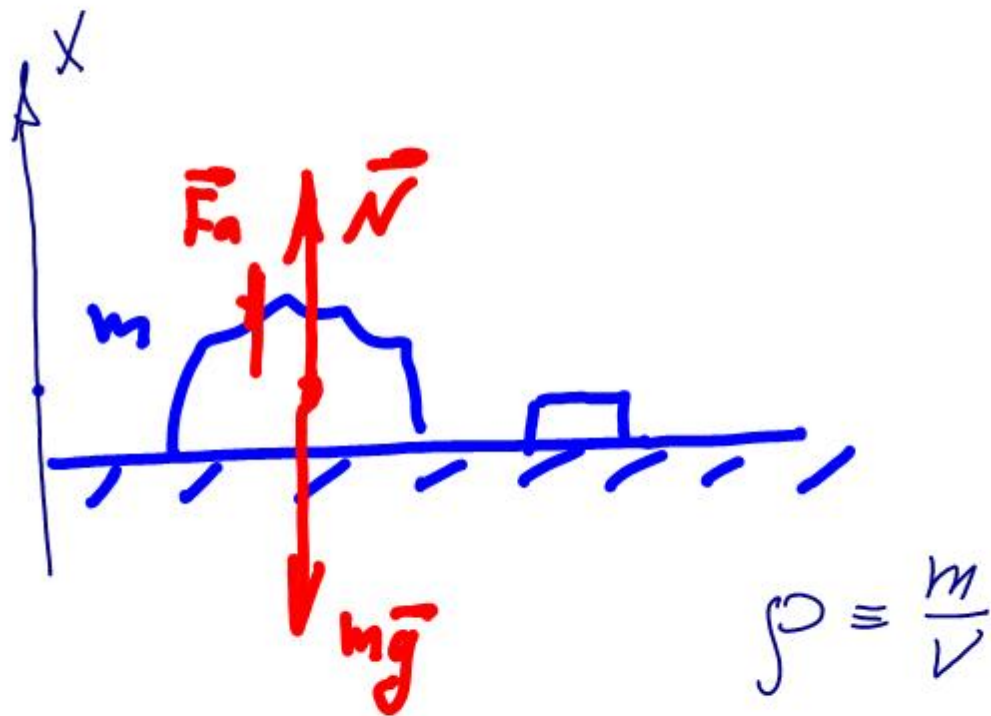


$$\frac{|\vec{F}|}{|\vec{a}|} \equiv m_u$$

- 1) m -macro
- 2) $m \geq 0$
- 3) $m \neq f(\vec{z}, \vec{v})$
- 4) $m = m_1 + m_2 + \dots + m_n$

$$\vec{a} = \frac{F}{m}$$





$$0 = m\vec{a} = m\vec{g} + \vec{N} + \vec{F}_a$$

$$0 = -mg + N + F_a$$

$$N = mg + F_a = mg + m'g =$$

$$= mg - \left(\frac{m}{\rho_T} \right) \cdot \rho_e g = mg \left(1 - \frac{\rho_e}{\rho_T} \right)$$

